

	Year 12 Pure and Stats	Pure C1 - Algebrai c expressi ons tra	i Pure C4 - Graphs and transformations Pure C5 - straight lin		phs - Circles		Vectors 8	Pure C12 - Di	fferentiation	Stats CI- data collection	Stats C2 locatio	2 - Measures of on and spread	Stats C3- S Represe ntation of data	itats C4 Correlati	Stats CS- Probability	Stats C6 - SI Distribu	atistical St tions Hypotl	ats C7 - nesis Testing						
Vear 12	Pupills will know:         - how to sketch cubic, quartic and reciprocal graphs;         - how to sketch cubic, quartic and reciprocal graphs;         - how to tandsmr graphs of unfamillar functions;         - how to tandsmr graphs of unfamillar functions;         - pupils will be able to:         - apply knowledge to solve problems.				Pupils will know: • circles; • how to find mag • model with vect Pupils will be abl • apply knowledg	Pupils will know: - circles; - how to find magnitude and direction of a vector; - model with vectors. Pupils will be able to: - apply knowledge to solve problems.			Pupils will know: - how to differentiate polynomials; - how to fink differentiation with gradient; - the different methods of collecting data. Pupils will be able to: - apply knowledge to solve problems.			Pupils will know: - measures of location and spread; - representations of dats; - correlation; - probability Pupils will be able to: - apply knowledge to solve problems.				Pupils will knowe       + the binomid distribution;       • hypothesis testing.       Pupils will be able to:       • apply knowledge to solve problems.								
	Year 12 Pure and Mechanics	Pure C2 - Quadratics	Pure C3 - Equations and Inequalities	Pure C8 - Binomial	Pure C7 - Algebraic me	Pure C9 - Trigonometr thods Ratios	c Pure C10 - Trig ider equation:	tities and Pure C14 - E 8 Mode	xponential Hing	Pure C13 - Integration		Mech C8 Modellin M		Mech C9 - Constant acceleration Mech C10 - Forces a		and Motion Mech C11 - Variable								
	Hours	b         5         4           Puplis wilk now:         - quadratic;         - quadratic;           - how to solve simultaneous equation;         - how to solve simultaneous equation;           - how to solve simultaneous equation;         - how to solve simultaneous equation;           - how to solve simultaneous equation;         - how to solve simultaneous equation;           - how to solve simultaneous equation;         - how to solve simultaneous equation;           - how to be able to:         - apply knowledge to solve problems.				Pupils will know: 5 0 - mathematical proof; - mathematical proof; - vipionomotric identities. Pupils will be able to: - apply knowledge to solve problems.			Pupils will know:         8           - how to solve trigonometric equations;         -           - exponential modelling;         -           - pupils will be able to:         -           - pupils will be able to:         -           - apply knowledge to solve problems.         -			2 0 / / Pupils will know: - modelling; - m			7	Pupils will • forces an • variable a Pupils will • apply known	5 d motion; ccceleration. be able to: owledge to solve	e problems.						
	Year 13 Pure and Stats	r 13 e and s Radians Trigonometric Trigonometry and mode			odelling Para	ling Parametric equations Differe			ntiation iequences and serie Binomial expansion			onditional probabilit The Normal distribution												
Year B	Hours	uns b 5 10 Puplis Will know: - radiant; - radiant; - radiant; - the solution of solution in a given range; - the solution and double angle formula. Puplis Will be able to: - apply knowledge to solve problems			Pupils will know: • trigonometry ar • parametric equi • the product rule Pupils will be abb • apply knowledg	b     b     c			Pupils will know: 7 4     Pupils will know:     how to differentiate:     its sequence of the sequence of the sequence of the sequence of the biomail expandence.     Pupils will be able to:     apply knowledge to solve problems.			3 5 8 Puplis will know regression, correlation and hypothesis testing; coordination at possibility; Puplis will be able to: sapply knowledge to solve problems.												
	Year 13 Pure and Mechanics	Algebraic methods	Functions and g	raphs Vectors	Moments	Forces and Friction	Projectiles Appl	ications of forces		Integration		Nume	rical methods F	urther Kinema	atics									
	Puglis will know:         - eligebrai methods;         - composite and inverse functions and their domain and range;         - modulus functions;         - roticuts;         - rotic					Pupils will know: • moments; • forces and friction; • projectiles. Pupils will be able to: • apply knowledge to solve problems.			Pupils will know: • application of forces; • integration. Pupils will be able to: • apply knowledge to solve problems.				Pupils will know: - numerical methods; - how to use vectors in kinematics. Pupils will be able to: - apply knowledge to solve problems.											